

# Variation of mode choice based on time of the day

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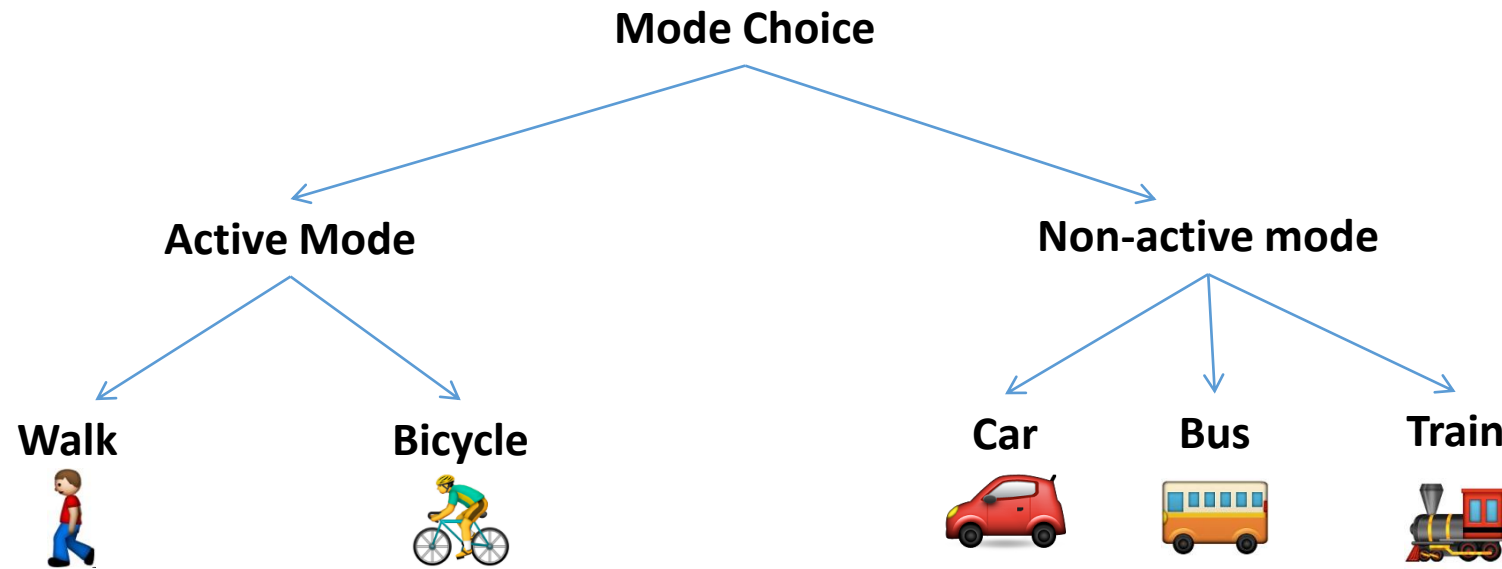
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# Primary structure of the Mode choice model



## Why a Nested Logit Model based on Active and Non-active modes?

- Travellers in general have a differentiated perception about modes that require physical activity ( active modes) from the non-active modes.
- Characteristics of traveller may influence active and non-active mode choice .
- Time of the day (peak/off-peak) and the purpose of the trip may affect the choice of active or non-active model of an individual.

```

25 pa <- x[6]
26 a1 <- x[7]
27 a2 <- x[8]
28 p1<-x[9]
29 p2<-x[10]
30 p3<-x[11]
31 p4<-x[12]
32 #a3 <- x[13]
33 #a4 <- x[10]
34 ## declare the log-likelihood variable, set value to 0
35 LL = 0

```

Our original utility function of nested logit model.

```

37 ## calculate the utility function: :introduce the desired explanatory variables in the function
38 train <- Data$ModeAvailableTrain*exp(d1*Data$TotalTimeTrain/100+p1*Data$Peak +b1*matrix(1,nrow =hh,ncol=1))
39 bus <- Data$ModeAvailableBus *exp(d1*Data$TotalTimeBus/100 +b2*matrix(1,nrow =hh,ncol=1))
40 car <- Data$ModeAvailableCar *exp(d1*Data$TimeCar/100+p2*Data$Peak +b3*matrix(1,nrow =hh,ncol=1))
41 bike <- Data$ModeAvailableBike *exp(d1*Data$TimeBike/100+p3*Data$Peak +b4*matrix(1,nrow =hh,ncol=1))
42 walk <- Data$ModeAvailableWalk *exp(d1*Data$TimeWalk/100+p4*Data$Peak )
43 ### Construct nests.First, calculate active or non-active choice probabilityP(LVI)
44 ## setting of log-sum variables
45 logsum.act <- log( ( (bike +walk)!=0) * (bike + walk) + ((bike+walk)==0))
46 logsum.nonact <- log( ( (car + bus+ train)!=0) * (car + bus+ train) + ((car + bus+ train)==0))

```

```

47
48 ##Calculate active or non-active choice probability with these log-sum variables
49 nume.act <- (logsum.act != 0)*exp(pa*logsum.act+a2*Data$Leisure) + (logsum.act == 0)
50 nume.nonact <- (logsum.nonact != 0)*exp(pa*logsum.nonact + a1*Data$AgeFemale45) + (logsum.nonact == 0)

```

```

51
52 deno <- nume.act + nume.nonact
53 P.act <- nume.act / deno
54 P.nonact <- nume.nonact / deno

```

Nested function

```

56   ### Next, calculate conditional probability.P(LV2|LV1)
57   ## conditional probability under active choice
58   deno.act      <- bike + walk
59   P.bike.act    <- bike / ((deno.act!=0)*deno.act + (deno.act==0))
60   P.walk.act    <- walk  / ((deno.act!=0)*deno.act+ (deno.act==0))
61
62   ## conditional probability non-active choice
63   deno.nonact   <- car + bus + train
64   P.car.nonact  <- car   / ((deno.nonact!=0)*deno.nonact + (deno.nonact==0))
65   P.bus.nonact  <- bus   / ((deno.nonact!=0)*deno.nonact + (deno.nonact==0))
66   P.train.nonact <- train / ((deno.nonact!=0)*deno.nonact + (deno.nonact==0))
67
68   ### Finally, calculate joint probability. P(LV1, LV2) = P(LV2|LV1)*P(LV1)
69   P.bike <- P.bike.act * P.act
70   P.walk  <- P.walk.act * P.act
71   P.car   <- P.car.nonact * P.nonact
72   P.bus   <- P.bus.nonact * P.nonact
73   P.train <- P.train.nonact * P.nonact
74   ## Avoid problems stemming from choice probabilities becoming zero.
75   P.train <- (P.train!=0)*P.train + (P.train==0)
76   P.bus   <- (P.bus!=0) *P.bus   + (P.bus==0)
77   P.car   <- (P.car!=0) *P.car   + (P.car==0)
78   P.bike  <- (P.bike!=0) *P.bike  + (P.bike==0)
79   P.walk  <- (P.walk!=0) *P.walk  + (P.walk==0)

```

```

80  ## Choice results
81  Ctrain  <- Data$MainModeENG == "Rail"
82  Cbus    <- Data$MainModeENG == "Bus"
83  Ccar    <- Data$MainModeENG == "Car"
84  Cbike   <- Data$MainModeENG == "Bicycle"
85  Cwalk   <- Data$MainModeENG == "Walk"
86  ## Calculate the Log-likelihood function
87  LL <- colSums(Ctrain*log(P.train) + Cbus*log(P.bus) + Ccar *log(P.car)  + Cbike *log(P.bike) +Cwalk *log(P.walk))
88
89  }
90  ##### Maximize the Log-likelihood function#####
91
92  ##Parameter optimization
93  res <- optim(b0,fr, upper=c(Inf, Inf, Inf, Inf, Inf, Inf), method = "L-BFGS-B", hessian = TRUE, control=
94
95  ## Parmeter estimation?Hessian matrix calculation
96  b    <- res$par
97  hhh <- res$hessian
98
99  ## Calculate the t-statistic
100  tval <- b/sqrt(-diag(solve(hhh)))
101
102  ## L(0), Log-Likelihood when all parameters are 0
103  L0 <- fr(b0)
104  ## LL, maximum likelihood
105  LL <- res$value

```

We calculate the scale parameter at first

```
> ##### Output #####
> print(res)
$par
 [1]  0.37973780 -1.94622631 -1.31251851 -1.08916068 -11.12017329 1.01370529  0.67255019  0.92477451  0.05081488
[10] -0.84076453 -0.91399755 -0.38458997

$value
 [1] -1260.269

$counts
function gradient
      66      66

$convergence
 [1] 0

$message
 [1] "CONVERGENCE: REL_REDUCTION_OF_F <= FACTR*EPSMCH"
```

And we got the answer of scale parameter as 1.01, which is very close to 1.

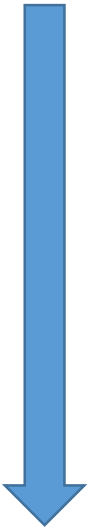
```

80  ## Choice results
81  Ctrain  <- Data$MainModeENG == "Rail"
82  Cbus    <- Data$MainModeENG == "Bus"
83  Ccar    <- Data$MainModeENG == "Car"
84  Cbike   <- Data$MainModeENG == "Bicycle"
85  Cwalk   <- Data$MainModeENG == "Walk"
86  ## Calculate the Log-likelihood function
87  LL <- colSums(Ctrain*log(P.train) + Cbus*log(P.bus) + Ccar *log(P.car)  + Cbike *log(P.bike) +Cwalk *log(P.walk))
88
89  }
90  ##### Maximize the Log-likelihood function#####
91
92  ##Parameter optimization
93  res <- optim(b0,fr, upper=c(Inf, Inf, Inf, Inf, Inf, 1, Inf), method = "L-BFGS-B", hessian = TRUE, control=list(fr
94
95  ## Parmeter estimation?Hessian matrix calculation
96  b    <- res$par
97  hhh <- res$hessian
98
99  ## Calculate the t-statistic
100  tval <- b/sqrt(-diag(solve(hhh)))
101
102  ## L(0), Log-Likelihood when all parameters are 0
103  L0 <- fr(b0)
104  ## LL, maximum likelihood
105  LL <- res$value

```

So we set the scale parameter as 1, then the model became a multinomial logit model.

```
> ##### Output #####
> print(res)
$par
[1] 0.37973780 -1.94622631 -1.31251851 -1.08916068 -11.12017329 1.01370529 0.67255019 0.92477451 0.05081488
[10] -0.84076453 -0.91399755 -0.38458997
$value
[1] -1260.269
$counts
function gradient
 66 66
> ##### Output #####
> print(res)
$par
[1] 0.38159200 -1.95083329 -1.32217701 -1.09506010 -11.17634759 1.00000000 0.67432473 0.92125786 0.05730248
[10] -0.83645881 -0.91138658 -0.38181228
$value
[1] -1260.282
$counts
function gradient
 48 48
$convergence
[1] 0
$message
[1] "CONVERGENCE: REL_REDUCTION_OF_F <= FACTR*EPSMCH"
```



**Nested logit model**

**Multinomial logit model**



```
> ## L(0)
> print(L0)
[1] -2158.061
```

```
> ## LL
> print(LL)
[1] -1260.269
```

```
> ##rho-square
> print((L0-LL)/L0)
[1] 0.416018
```

```
> ## adjusted rho-square
> print((L0-(LL-length(b)))/L0)
[1] 0.4104575
```

```
> ## L(0)
> print(L0)
[1] -2158.061
```

```
> ## LL
> print(LL)
[1] -1260.282
```

```
> ##rho-square
> print((L0-LL)/L0)
[1] 0.4160121
```

```
> ## adjusted rho-square
> print((L0-(LL-length(b)))/L0)
[1] 0.4104516
```

**Original nested logit model**

**Multinomial logit model**

```
> ##estimated parameter values
> print(b)
[1] 0.37973780 -1.94622631 -1.31251851 -1.08916068 -11.12017329 1.01370529 0.67255019 0.92477451 0.05081488
[10] -0.84076453 -0.91399755 -0.38458997
```

```
> ## t-statistic
> print(tval)
[1] 2.405447 -6.366029 -8.154827 -7.590359 -17.256611 11.604624 2.170456 2.318519 0.131675 -2.238590
[11] -2.374214 -1.003533
```

Peak or Non peak  
explanatory variable

According to our model, it means if  
the travel time increase, the  
possibility of choosing the  
alternative is decreasing.

Nested logit model

Multinomial logit model

```
> ##estimated parameter values
> print(b)
[1] 0.38159200 -1.95083329 -1.32217701 -1.09506010 -11.17634759 1.00000000 0.67432473 0.92125786 0.05730248
[10] -0.83645881 -0.91138658 -0.38181228
```

```
> ## t-statistic
> print(tval)
[1] 2.4021272 -6.3675545 -8.1721911 -7.6274878 -17.3352552 11.6569103 2.1793043 2.3165880 0.1482927
[10] -2.2247825 -2.3608487 -0.9931024
```

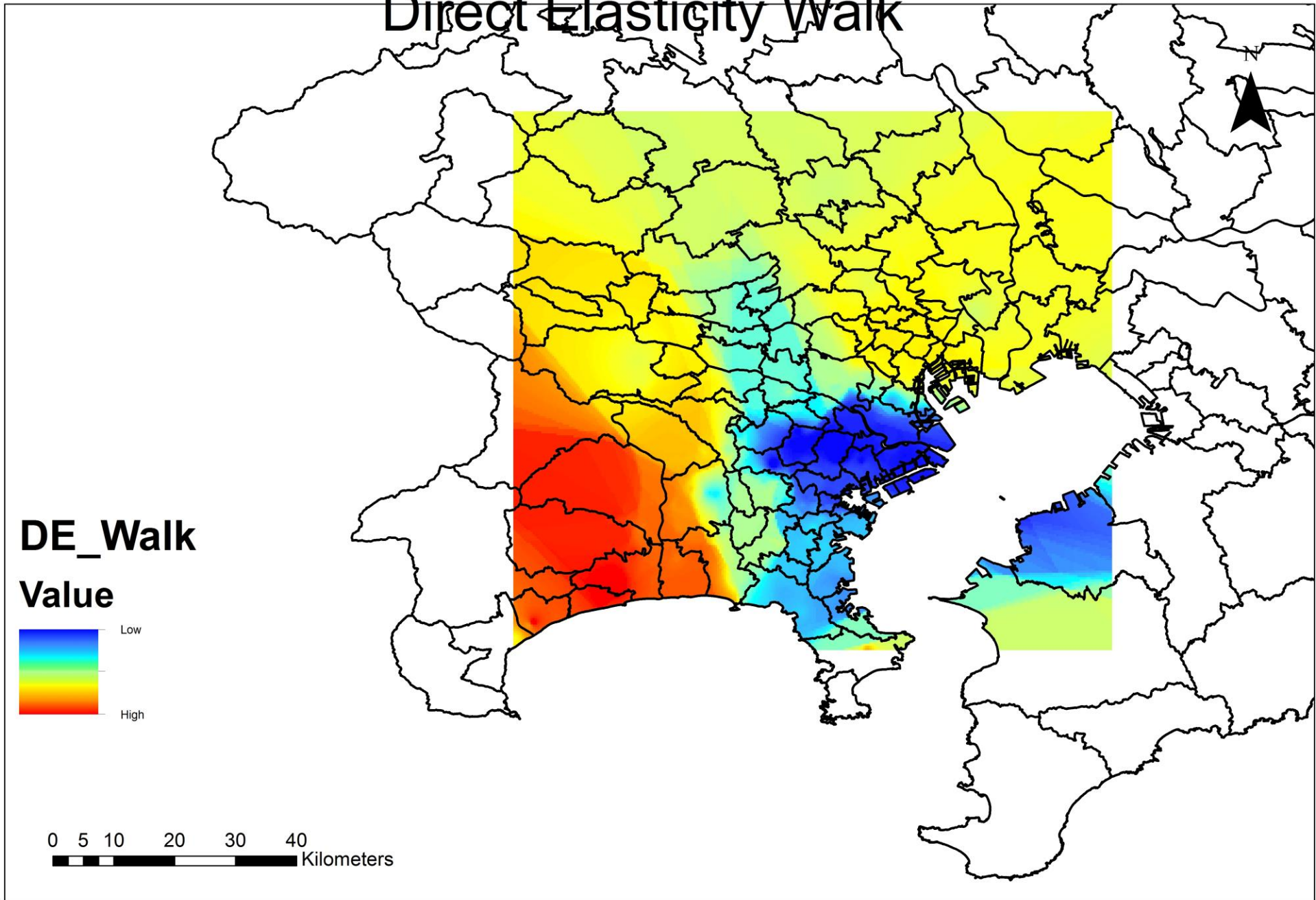
# Elasticity based on distance

Distance		DE_bike time	DE_walk time	DE_car time	DE_bus time	DE_train time
Less than 1km	Mean	-.42	-.63	-.56	-.12	-.74
	N	334.00	334.00	334.00	334.00	334.00
	Std. Deviation	.17	.28	.30	.16	1.06
1km-3km	Mean	-1.18	-1.97	-1.13	-.41	-1.87
	N	342.00	342.00	342.00	342.00	342.00
	Std. Deviation	.36	.66	.35	.56	1.07
3km-5km	Mean	-2.63	-4.22	-1.87	-.41	-2.61
	N	115.00	115.00	115.00	115.00	115.00
	Std. Deviation	.48	.89	.47	.90	1.20
5km-10km	Mean	-5.07	-7.03	-2.73	-.07	-2.41
	N	120.00	120.00	120.00	120.00	120.00
	Std. Deviation	1.02	1.31	.56	.48	1.04
Gretear than 10km	Mean	-14.62	-12.41	-6.41	-.08	-6.09
	N	611.00	611.00	611.00	611.00	611.00
	Std. Deviation	6.29	2.63	2.43	.46	3.00
Total	Mean	-6.83	-6.44	-3.31	-.19	-3.42
	N	1522.00	1522.00	1522.00	1522.00	1522.00
	Std. Deviation	7.63	5.45	3.04	.51	3.07

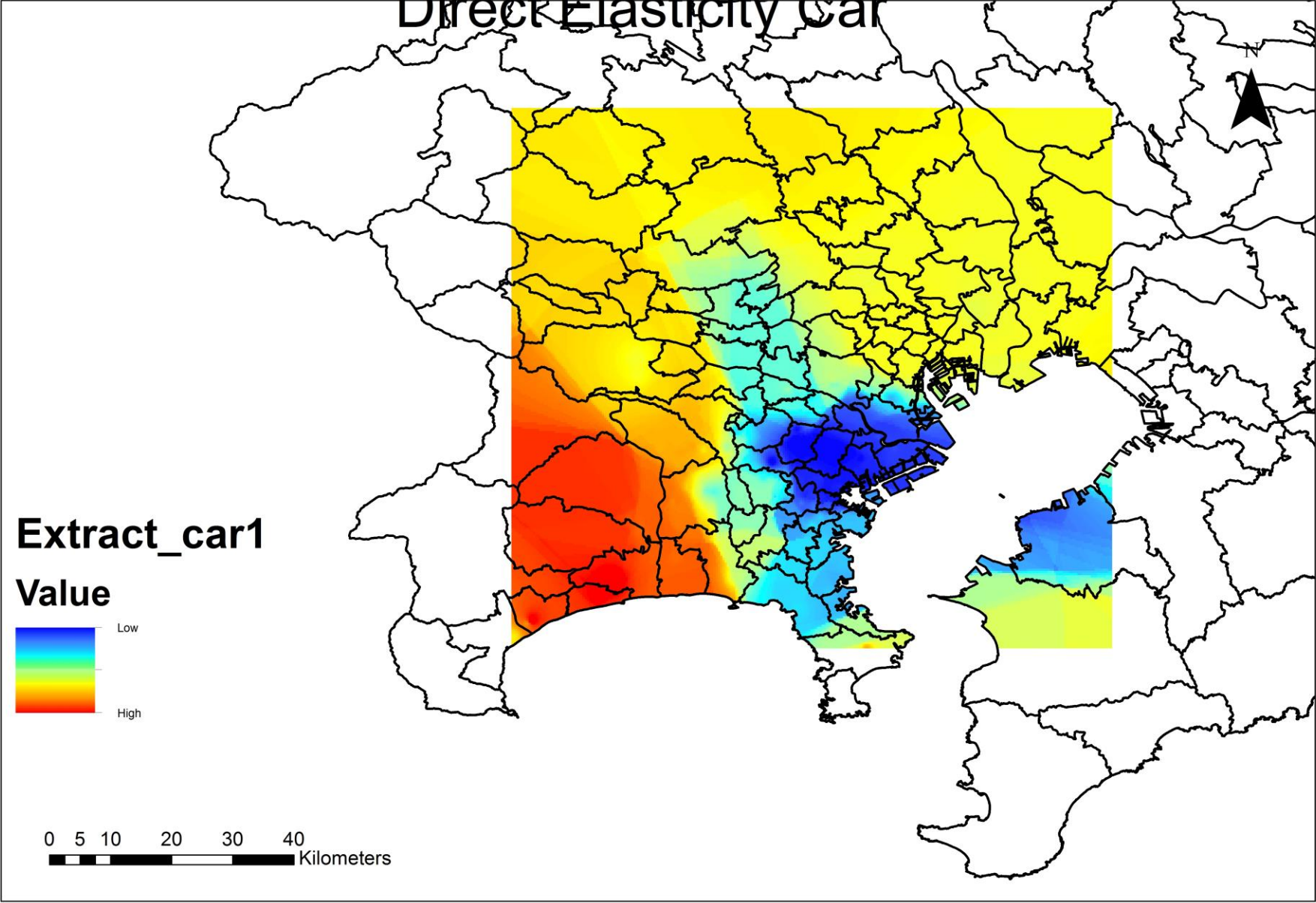
## Cross Elasticity

<b>Wavg_bike</b>	<b>Wavg_walk</b>	<b>Wavg_car</b>	<b>Wavg_bus</b>	<b>Wavg_train</b>	<b>Distance</b>
0.06	0.71	0.21	0.17	1.95	a) less than 1 km
0.11	1.19	0.15	0.17	2.2	b) 1km-3km
0.22	2.85	0.19	0.12	2.88	c) 3km-5km
0.33	6.42	0.14	0.15	1.9	d) 5km-10km
0.35	26.95	0.21	0.08	2.82	e) Greater than 10km

# Direct Elasticity Walk

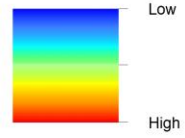


# Direct Elasticity Car



Extract\_car1

Value



# Conclusion

- MNL structure most appropriate for the model
- Variation in elasticities plotted based on distance and spatially
- Elasticities increase with increasing distance for all modes.
- Spatial variation in elasticity for modes can be used for targeted policies in designated areas.

Thank You